



# Kxx V

## INDICATORS with independent Timer



### Engineering Manual

Code: ISTR-MKVENG20- Vr. 2.0 (ENG)

**Ascon Tecnologic S.r.l.**

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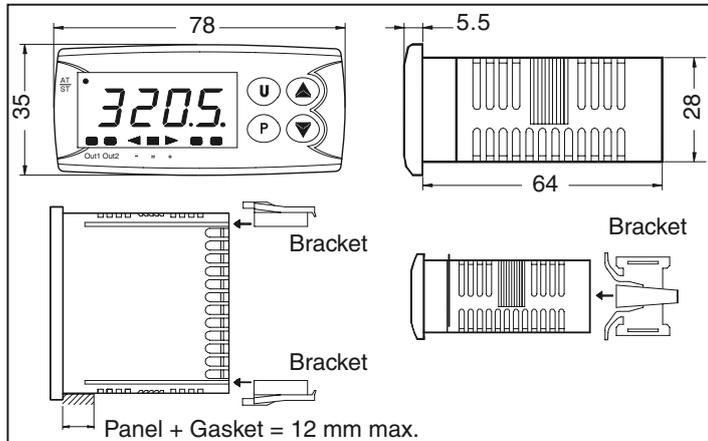
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www.ascontecnologic.com

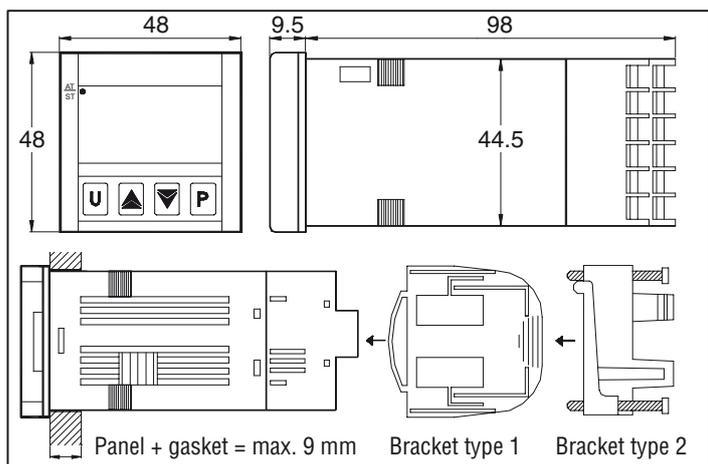
e-mail: info@ascontecnologic.com

## 1. OUTLINE DIMENSIONS (MM)

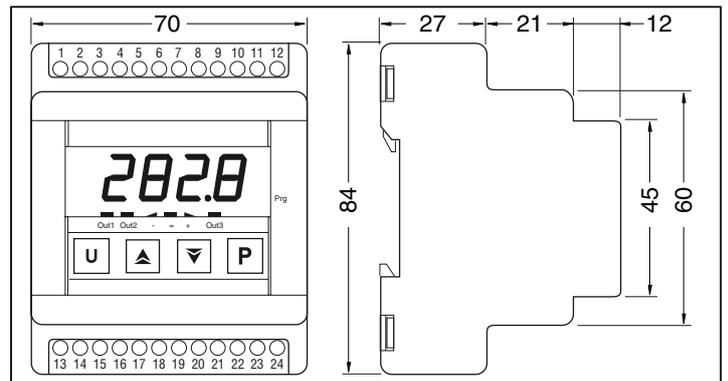
### 1.1 3xV Series



### 1.2 K48 V Series



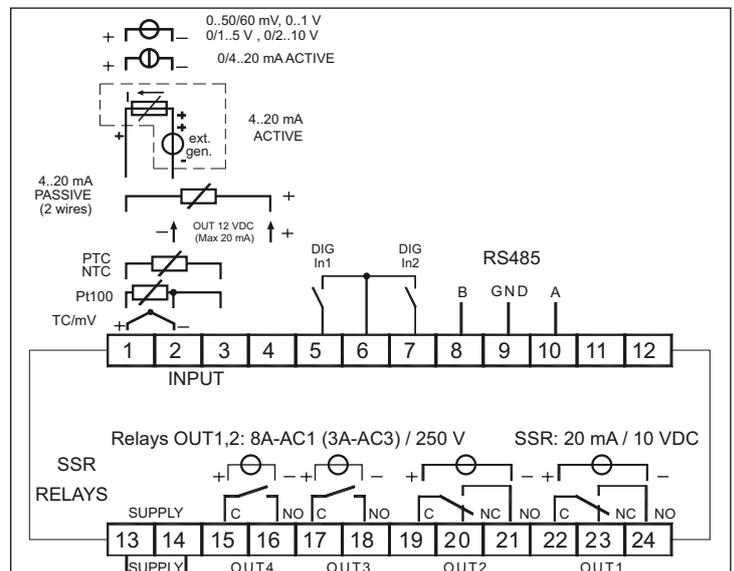
### 1.3 K85 V Series



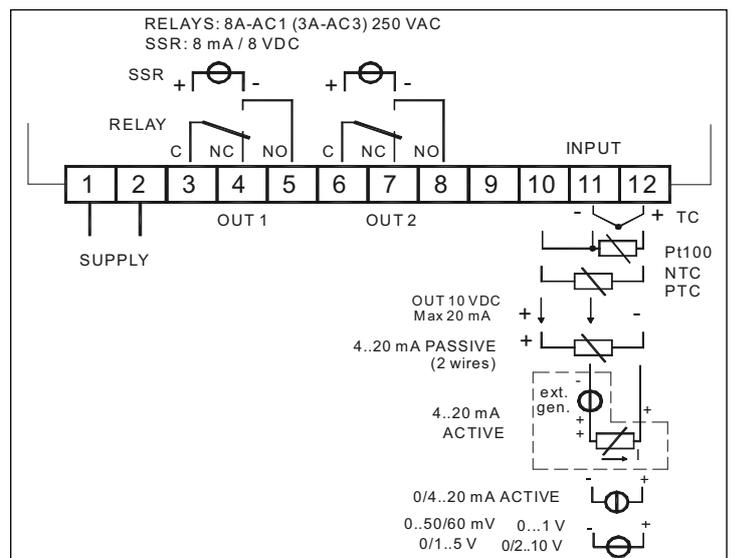
## 2. CONNECTIONS

### 2.1 Connection Diagrams

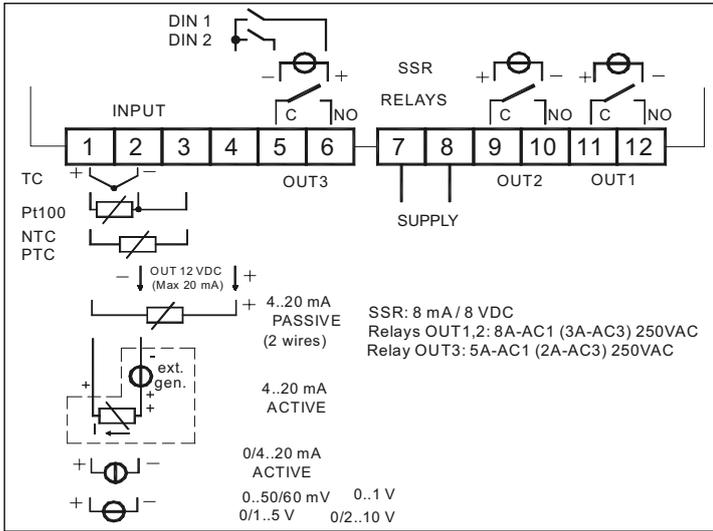
#### 2.1.1 K31 V Series



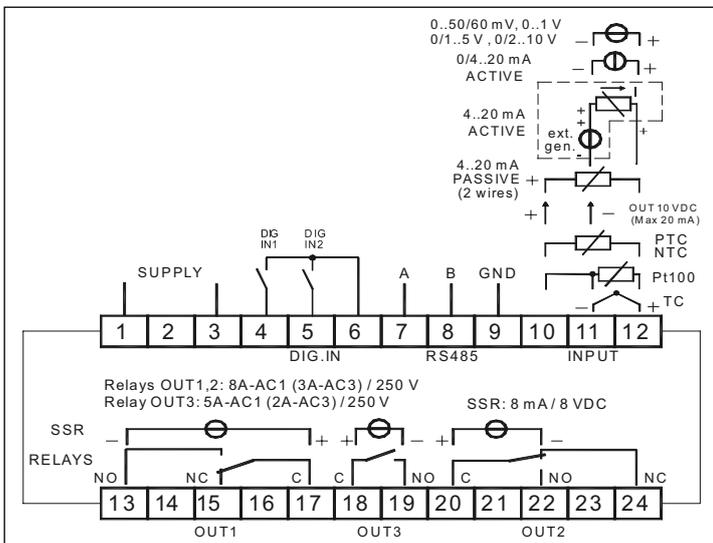
#### 2.1.2 K38 V Series



### 2.1.3 K48V Series



### 2.1.4 K85V Series



## 2.2 Mounting Requirements

This instrument is intended for permanent installation, for indoor use only, in an electrical panel which encloses the rear housing, exposed terminals and wiring on the back.

Select a mounting location having the following characteristics:

1. It should be easily accessible;
2. There is minimum vibrations and no impact;
3. There are no corrosive gases;
4. There are no water or other fluid (i.e. condensation);
5. The ambient temperature is in accordance with the operative temperature (0... 50°C);
6. The relative humidity is in accordance with the instrument specifications ( 20% to 85 %).

Lo strumento può essere montato su un pannello con uno spessore massimo di 15 mm.

Per ottenere la massima protezione frontale (IP65), è necessario montare la guarnizione opzionale.

## 2.3 General Notes about Input Wiring

1. Do not run input wires together with power cables;
2. External components (like zener barriers, etc.) connected between sensor and input terminals may cause errors in measurement due to excessive and/or not balanced line

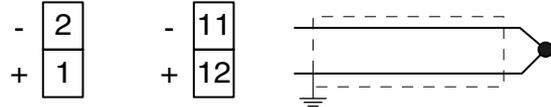
resistance or possible leakage currents;

3. When a shielded cable is used, it should be connected at one point only;
4. Pay attention to the line resistance; a high line resistance may cause measurement errors.

## 2.4 Inputs wiring

### 2.4.1 Ingresso da termocoppia

**K31-K48 K38-K85**



**External resistance:** 100 Ω max., maximum error 0.5% of span.

**Cold junction:** automatic compensation from 0 to 50°C.

**Cold junction accuracy:** 0.1°C/°C after a warm-up of 20 minutes.

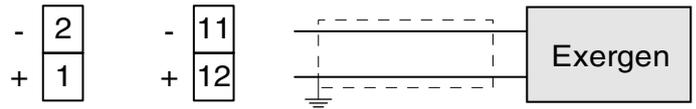
**Input impedance:** > 1 MΩ.

**Calibration:** according to EN 60584-1.

**Note:** For TC wiring use proper compensating cable preferable shielded.

### 2.4.2 Infrared Sensors Input

**K31-K48 K38-K85**



**External resistance:** Do not care condition.

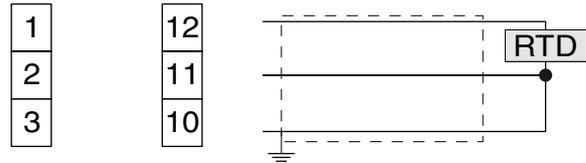
**Cold junction:** Automatic compensation from 0 to 50°C.

**Cold junction accuracy:** 0.1°C/°C.

**Input impedance:** > 1 MΩ.

### 2.4.3 RTD (PT100) Input

**K31-K48 K38-K85**



**Input circuit:** Current injection (135 μA).

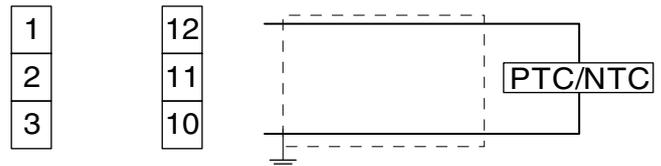
**Line resistance:** Automatic compensation up to 20Ω/wire with maximum error ±0.1% of the input span.

**Calibration:** According to EN 60751/A2.

**Note:** The resistance of the 3 wires must be the same.

### 2.4.4 Thermistors Input

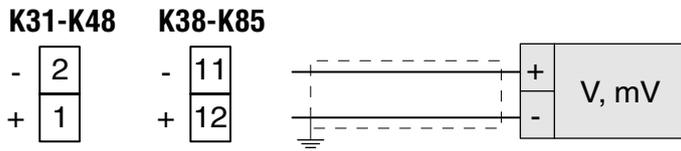
**K31-K48 K38-K85**



**Line resistance:** Not compensated.

**Pt 1000 Input circuit:** Current injection (25 μA).

## 2.4.5 V and mV Input

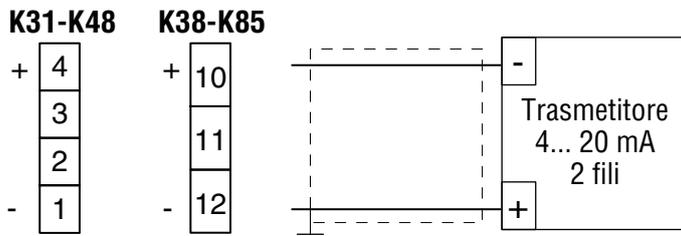


**Input impedance:** > 1 MΩ

**Accuracy:** ±0.5 % of Span ±1 digit @ 25 °C.

## 2.4.6 Current Input (mA)

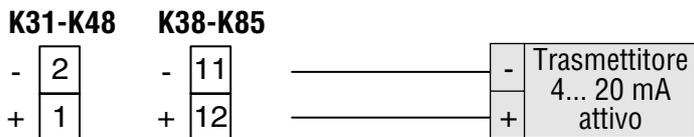
*0/4... 20 mA input wiring for passive transmitter using auxiliary pws*



*0/4... 20 mA input wiring for passive transmitter using an external pws*



*0/4... 20 mA input wiring for active transmitter*



**Input impedance:** < 51Ω.

**Accuracy:** 0.5% of Span ±1 dgt @ 25 °C.

**Protection:** NOT protected from short circuit.

**Internal auxiliary PWS:** 10 VDC (±10%), 20 mA max..

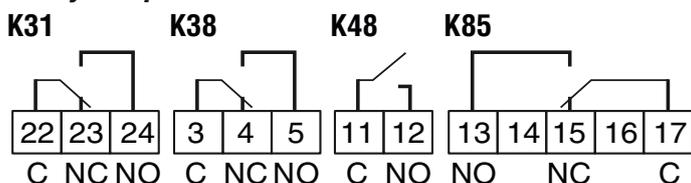
## 2.5 Output

### Safety notes:

- To avoid electrical shock, connect power line at last.
- For supply connections use No. 16 AWG or larger wires rated for at last 75°C;
- Use copper conductors only.
- SSR outputs are not isolated. A double or reinforced isolation must be assured by the external solid state relays.

### 2.5.1 Output 1 (OP1)

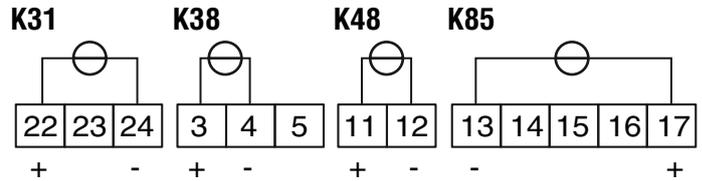
#### Relay Output



**Out 1 contact rating:** • 8 A /250 V cosφ =1;  
• 3 A /250 V cosφ =0.4.

**Operation:** 1 x 10<sup>5</sup>.

### Uscita SSR

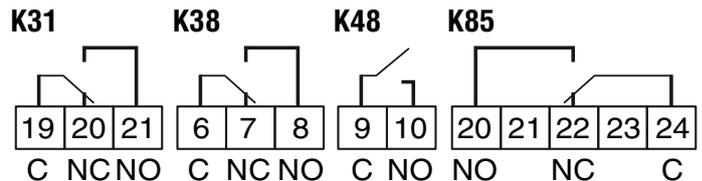


**Logic level 0:** Vout < 0.5 VDC;

**Logic level 1:** 12 V ±20% @ 1 mA;  
10 V ±20% @ 20 mA.

### 2.5.2 Output 2 (OP2)

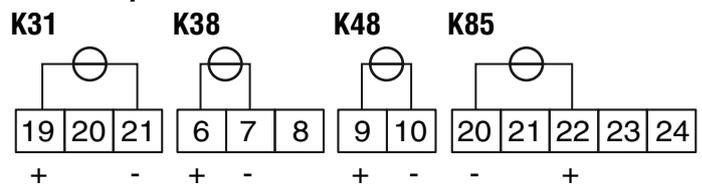
#### Relay Output



**Out 2 contact rating:** • 8 A /250 V cosφ =1;  
• 3 A /250 V cosφ =0.4.

**Operation:** 1 x 10<sup>5</sup>.

#### SSR Output

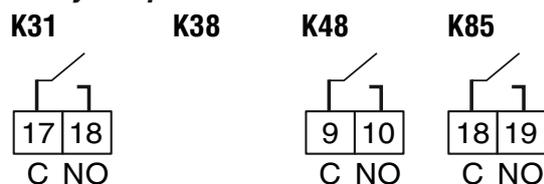


**Logic level 0:** Vout < 0.5 VDC;

**Logic level 1:** 12 V ±20% @ 1 mA;  
10 V ±20% @ 20 mA.

### 2.5.3 Output 3 (OP3)

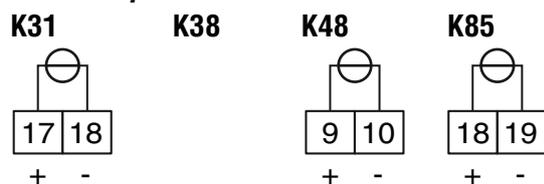
#### Relay Output



**Out 3 contact rating:** • 8 A /250 V cosφ =1;  
• 3 A /250 V cosφ =0.4.

**Operation:** 1 x 10<sup>5</sup>.

#### SSR Output



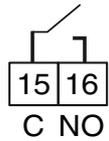
**Logic level 0:** Vout < 0.5 VDC;

**Logic level 1:** 12 V ± 20% @ 1 mA;  
10 V ± 20% @ 20 mA.

## 2.5.4 Output 4 (OP4)

### Relay Output

**K31**



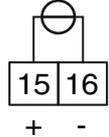
**Out 1 contact rating:**

- 8 A /250 V  $\cos\phi = 1$ ;
- 3 A /250 V  $\cos\phi = 0.4$ .

**Operation:**  $1 \times 10^5$ .

### SSR Output

**K31**



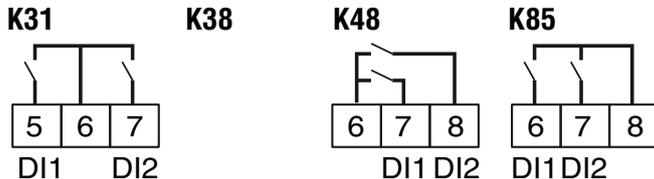
**Logic level 0:**  $V_{out} < 0.5 \text{ VDC}$ ;

**Logic level 1:**  $12 \text{ V} \pm 20\% @ 1 \text{ mA}$ ;  
 $10 \text{ V} \pm 20\% @ 20 \text{ mA}$ .

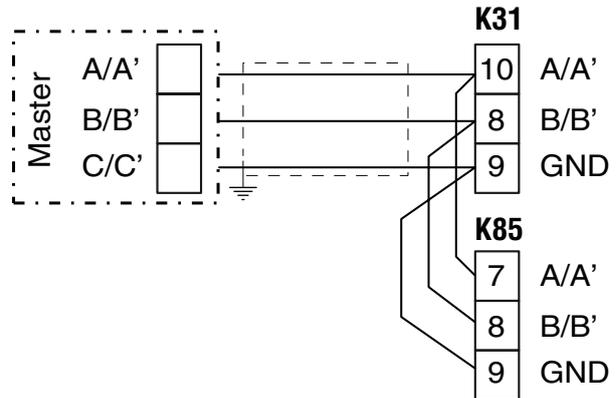
## 2.6 Logic Inputs

### Safety notes:

- Do not run logic input wiring together with power cables.
- Use an external dry contact capable to switch 0.5 mA, 5 VDC.
- The instrument needs 150 ms to recognize a contact status variation.
- The logic inputs are **NOT** isolated by the measuring input. A double or reinforced isolation between logic inputs and power line must be assured by the external element.



## 2.7 Serial Interface



**Interface type:**

- Isolated (50 V) RS-485;
- TTL not isolated;

**Voltage levels:** According to EIA standard;

**Protocol type:** MODBUS RTU;

**Byte format:** 8 bit without parity;

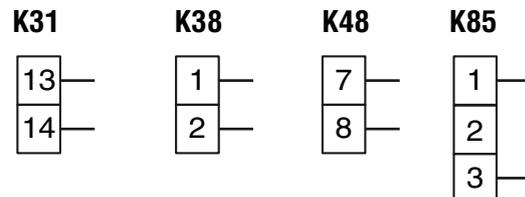
**Stop bit:** One;

**Baud rate:** Programmable: 1200... 38400 baud;

**Address:** Programmable: 1... 255.

- Notes:**
1. RS-485 interface allows to connect up to 30 devices with one remote master unit.
  2. The cable length must not exceed 1.5 km at 9600 baud.

## 2.8 Power Supply



**Supply voltage:**

- 12 VAC/DC ( $\pm 10\%$ );
- 24 VAC/DC ( $\pm 10\%$ );
- 100... 240 VAC ( $\pm 10\%$ ).

**Power Consumption:** 5 VA max.

- Notes:**
1. Before connecting the instrument to the power line, make sure that line voltage is equal to the voltage shown on the identification label;
  2. To avoid electrical shock, connect power line at the end of the wiring procedure.
  3. For supply connections use No 16 AWG or larger wires rated for at least 75 °C.
  4. Use copper conductors only.
  5. For power supply the polarity is a do not care condition.
  6. The power supply input is NOT fuse protected.
  7. Please, provide a T type 1A, 250 V external fuse.

### 3. TECHNICAL CHARACTERISTICS

#### 3.1 Technical Specifications

**Case:** Plastic, self-extinguishing degree: V-0 according to UL 94;

**Front protection:** IP 65 (when the optional panel gasket is mounted) for indoor locations according to EN 60070-1.

**Rear terminals protection:** IP 20 according to EN 60070-1.

**Terminal block:** Screw terminals (screw M3, for cables of 0.25... 2.5 mm<sup>2</sup> or from AWG 22 to AWG 14) with connection diagrams.

**Dimensions:**

**K3xV:** 78 x 35 x 64 mm (3.07 x 1.38 x 2.52")

**K4xV:** 48 x 48 x 98 mm (1.77 x 1.77 x 3.86")

**K85V:** 70 x 84 x 60 mm (2.76 x 3.31 x 2.37");

**Mount cut-out:**

**K3xV:** 71(+0.6) x 29(+0.6) mm [2.8(+0.023) x 1.78(+0.023) in.];

**K4xV:** 45(+0.6) x 45(+0.6) mm [1.78(+0.023) x 1.78(+0.023) in.];

**K85V:** DIN rail mounting.

**Weight:** About 180 g;

**Power Supply:**

- 12 VAC/DC ( $\pm 10\%$  of the nominal voltage);

- 24 VAC/DC ( $\pm 10\%$  of the nominal voltage);

- 100... 240 VAC (-15... +10% of the nominal voltage);

**Power consumption:** 5 VA max.;

**Insulation voltage:** 2300 V rms according to EN 61010-1;

**Display:** One 4 digits red display h 12 mm + 3 LED Bargraph;

**Display updating time:** 500 ms;

Sampling time: 130 ms;

Resolution: 30000 counts;

**Total Accuracy:**  $\pm 0.5\%$  F.S.V.  $\pm 1$  digit @ 25°C of room temperature;

**Common mode rejection:** 120 dB at 50/60 Hz;

**Normal mode rejection:** 60 dB at 50/60 Hz;

**Electromagnetic compatibility and safety requirements**

**Compliance:** - directive EMC 2004/108/CE (EN 61326-1),  
- directive LV 2006/95/CE (EN 61010-1);

**Installation category:** II;

**Pollution category:** 2;

**Temperature drift:** It is part of the global accuracy;

**Operating temperature:** 0... 50°C (32... 122°F);

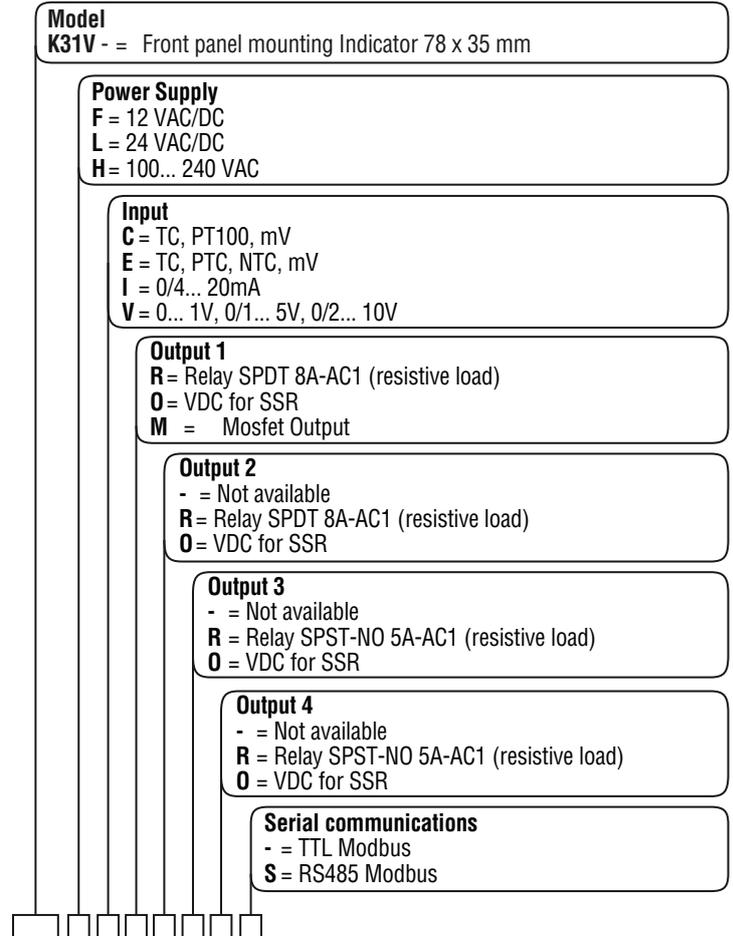
**Storage temperature:** -30... +70°C (-22... 158°F);

**Humidity:** 20... 85% RH, non condensing;

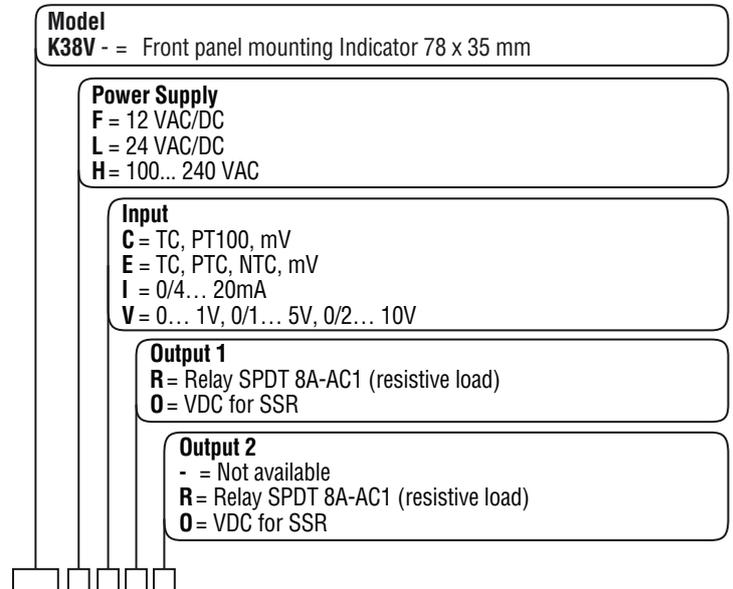
**Protections:** WATCH DOG (hardware/software) for the automatic restart.

### 4. HOW TO ORDER

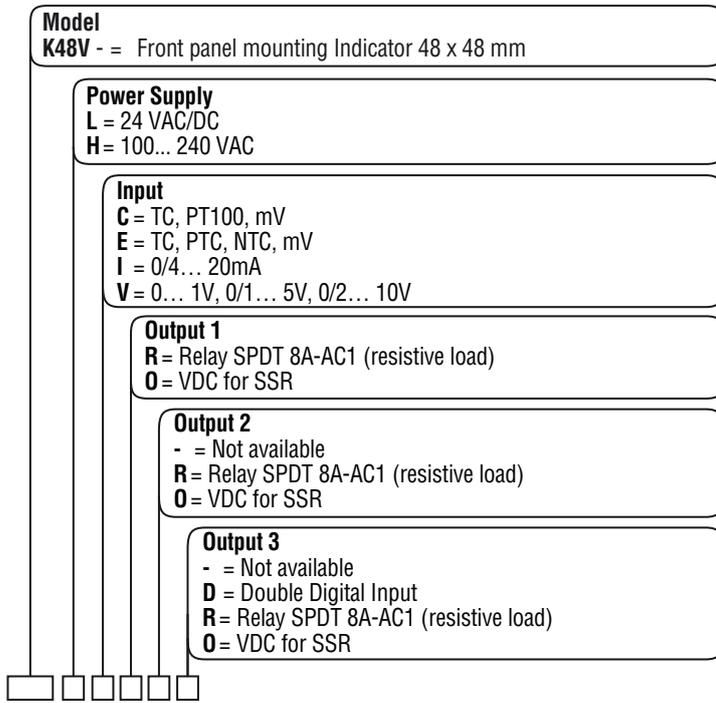
#### 4.1 K31V



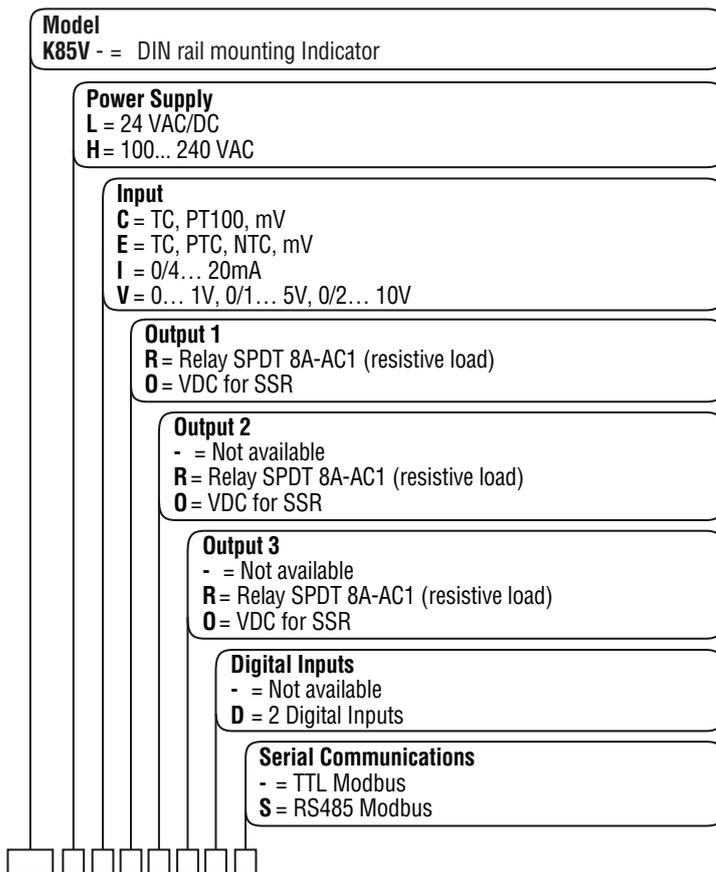
#### 4.2 K38V



### 4.3 K48V



### 4.4 K85V



## 5. CONFIGURATION PROCEDURE

### 5.1 Introduction

When the instrument is powered, it starts immediately to work according to the parameters values loaded in its memory.

The instrument behaviour and its performances are governed by the value of the memorized parameters.

At the first start up the instrument will use a “default” parameter set (factory parameter set); this set is a generic one (e.g. a TC J input is programmed).

We recommend that you modify the parameter set to suit your application (e.g. set the right input type, define the alarms, etc.)

To change these parameters you will need to enter the “Configuration procedure”.

#### 5.1.1 Access levels to the parameter modifications and their password

The instrument have one complete parameter set.

We call this set “configuration parameter set” (or “configuration parameters”).

The access to the configuration parameters is protected by a programmable password (password level 3).

The configuration parameters are collected in various groups. Every group defines all parameters related with a specific function (E.g. alarms, output functions, serial link).

**Note:** Note the instrument will show only the parameters consistent with the specific hardware and in accordance with the value assigned to the previous parameters (e.g. if you set an output as “not used” the instrument will mask all other parameters related with this output).

### 5.2 Instrument Behaviour at Power UP

At power up the instrument can show one of the following information:

- The display will show the measured value;
- The display will show one alarm threshold;
- The display will show programmed time of the timer.

in all cases:

- The the programmed alarm are enabled;
- The serial link is immediately operative.

We define the above conditions as “Standard Display”.

### 5.3 How to enter the Configuration Mode

1. Push the **[P]** button for more than 3 seconds.

The display will show alternately **0** and «*PASS*».

2. Using **[▲]** and/or **[▼]** buttons set the programmed password.

**Notes:** 1. The factory default password for configuration parameters is equal to 30.

2. All parameter modification are protected by a time out. If no button is pressed for more than 10 second the instrument return automatically back to the Standard display, the new value of the last selected parameter is lost and the parameter modification procedure is closed.

When you desire to remove the time out (e.g. for the first configuration of an instrument) you can use a password equal to 1000 plus the programmed

password (e.g. 1000 + 30 [default] = 1030). It is always possible to end manually the parameter configuration procedure (see the next paragraph).

3. During parameter modification the instrument continue to perform the control. In certain conditions, when a configuration change can produce a heavy bump to the process, it is advisable to temporarily stop the controller from controlling during the programming procedure (its control output will be Off). A password equal to 2000 + the programmed value (e.g. 2000 + 30 = 2030).

The control will restart automatically when the configuration procedure will be manually closed.

3. Push the **[P]** button. If the password is correct the display will show the acronym of the first parameter group preceded by the symbol **↵**.

In other words the display will show: **↵ 100P**

The instrument is in configuration mode.

### 5.4 How to exit the Configuration Mode

Push the **[U]** button for more than 5 seconds.

The instrument will come back to the “standard display”

### 5.5 Funzione dei tasti durante la modifica dei parametri

**[U]** A short press allows to exit from the current parameter group and select a new parameter group.

A long press allows you to close the configuration parameter procedure (the instrument will come back to the “standard display”).

**[P]** When the upper display is showing a group and the lower display is blank, this key allows to enter in the selected group.

When the upper display is showing a parameter and the lower display is showing its value, this key allows to store the selected value for the current parameter and access the next parameter within the same group.

**[▲]** Allows to increase the value of the selected parameter.

**[▼]** Allows to decrease the value of the selected parameter.

**Note:** The group selection is cyclic as well as the selection of the parameters in a group.

### 5.6 Factory Reset - Default Parameters Loading Procedure

Sometime, e.g. when you reconfigure an instrument previously used for other works or from other people or when you have made too many errors during configuration and you decided to reconfigure the instrument, it is possible to restore the factory configuration.

This action allows you to put the instruent in a defined condition (in the same condition it was at the first power up).

The default data are the typical values loaded in the instrument prior to shipment from factory.

To load the factory default parameter set, proceed as follows:

1. Press the **[P]** button for more than 5 seconds;
2. The upper display will show “*PASS*” while the lower display shows “**0**”;
3. Press the **[▲]** and/or **[▼]** buttons to set the *-48* value;
4. Press the **[P]** button;
5. The instrument will turn OFF all LEDs for a few seconds,

then the upper display will show  $dFLt$  (default) and then all LEDs are turned ON for 2 seconds. At this point the instrument restarts as for a new power ON.

The procedure is complete.

**Note:** The complete list of the default parameters is available in Appendix A.

## 5.7 Configuring all the Parameters

In the following pages we will describe all the parameters of the instrument. However, the instrument will only show the parameters applicable to its hardware options in accordance with the specific instrument configuration (i.e. setting  $RLIt$  [Alarm 1 type] to  $nonE$  [not used], all parameters related to alarm 1 will be skipped).

### **2**inP Group - Main and auxiliary input configuration

#### [2] $SEnS$ - Input Type

**Available:** Always.

**Range:** • When the code of the input type is equal to  **C** (see Ordering Code at page 29).

J = TC J (0... 1000°C/32... 1832°F)  
 crAL = TC K (0... 1370°C/32... 2498°F)  
 S = TC S (0... 1760°C/32... 3200°F)  
 r = TC R (0... 1760°C/32... 3200°F)  
 t = TC T (0... 400°C/32... 752°F)  
 ir.J = Exergen IRS J (0... 1000°C/32... 832°F)  
 ir.cA = Exergen IRS K (0... 1370°C/32... 2498°F)  
 Pt1 = RTD Pt 100 (-200... 850°C/-328... 1562°F)  
 0.50 = 0... 50 mV linear  
 0.60 = 0... 60 mV linear  
 12.60 = 12... 60 mV linear

• When the code of the input type is equal to  **E**.

J = TC J (0... 1000°C/32... 1832°F)  
 crAL = TC K (0... 1370°C/32... 2498°F)  
 S = TC S (0... 1760°C/32... 3200°F)  
 r = TC R (0... 1760°C/32... 3200°F)  
 t = TC T (0... 400°C/32... 752°F)  
 ir.J = Exergen IRS J (0... 1000°C/32... 1832°F)  
 ir.cA = Exergen IRS K (0... 1370°C/32... 2498°F)  
 Ptc = PTC KTY81-121 (-55... 150°C/-67... 302°F)  
 0.50 = 0... 50 mV linear  
 0.60 = 0... 60 mV linear  
 12.60 = 12... 60 mV linear

• When the code of the input type is equal to  **I**.

0.20 = 0... 20 mA linear  
 4.20 = 4... 20 mA linear

• When the code of the input type is equal to  **V**.

0.1 = 0... 1 V linear  
 0.5 = 0... 5 V linear  
 1.5 = 1... 5 V linear  
 0.10 = 0... 10 V linear  
 2.10 = 2... 10 V linear

**Notes:** 1. When a TC input is selected and a decimal figure is programmed (see the next parameter) the max. displayed value become 999.9°C or 999.9°F

2. Every change of the  $SEnS$  parameter setting will force the following change:

[3] dP = 0  
 [129] ES.L = -1999  
 [130] ES.H = 9999

#### [3] dP - Decimal point position

**Available:** Always.

**Range:** When [2]  $SEnS$  = Linear input: 0 to 3.  
 When [2]  $SEnS$  different from linear input: 0 or 1

**Note:** Every change of the dP parameter setting will produce a change of the parameters related with it (e.g. Alarm thresholds, Peak hi and peak low memory, etc.).

#### [4] $SSc$ - Initial scale read-out for linear inputs

**Available:** When a linear input is selected by [2]  $SEnS$ .

**Range:** -1999 to 9999

- Notes:**
1. It defines the value shown by the instrument when it measures the the minimum electrical value of the scale selected by [2]  $SEnS$  parameter
  2. It allows the scaling of the analogue input to set the minimum displayed/measured value  
 The instrument will show a measured value up to 5% less then  $SSc$  value and than it will show an underrange error.
  3. It is possible to set a initial scale read-out higher than the full scale read-out in order to obtain a reverse read-out scaling.  
 E.g. 0 mA = 0 mBar and 20 mA = - 1000 mBar (vacuum).

#### [5] $FSc$ - Full scale read-out for linear input

**Available:** When a linear input is selected by [2]  $SEnS$ .

**Range:** -1999... +9999.

- Notes:**
1. - It defines the value shown by the instrument when it measures the the maximum electrical value of the scale selected by [2]  $SEnS$  parameter
  2. - It allows the scaling of the analogue input to set the maximum displayed/measured value  
 The instrument will show a measured value up to 5% higher than [5]  $FSc$  value and then it will show an overrange error.
  3. It is possible to set a full scale read-out lower than the initial scale read-out in order to obtain a reverse read-out scaling.  
 E.g. 0 mA = 0 mBar and 20 mA = - 1000 mBar (vacuum).

#### [6] 0.Pot - Offset value used to shift the readout zero

**Available:** When a linear input is selected by [2]  $SEnS$ .

**Range:** -1999... +9999 engineering units.

#### [7] unit - Engineering unit

**Available:** When a temperature sensor is selected by [2]  $SEnS$ .

**Range:** °c = Centigrade  
 °F = Fahrenheit

#### [8] FiL - Digital filter on the measured value

**Available:** Always.

**Range:** oFF (No filter) 0.1 to 20.0 s.

**Note:** This is a first order digital filter applied on the measured value. For this reason it will affect both the measured value but also the control action and the alarms behaviour.

#### [9] diF1 - Digital input 1 function

**Available:** When the instrument is equipped with digital inputs.

**Range:** oFF = No function.

AAC = Alarm Reset [status]  
 ASi = Alarm acknowledge (ACK) [status].  
 HoLd = Hold of the measured value [status].  
 r.Pic = Peaks reset [transition]  
 0.Pot = start of the 0.Pot procedure. [transition]  
 r.PoP = Start of the 0.Pot procedure and Peaks reset [transition]  
 t.rHr = Timer Run/Hold/Reset [transition]  
 t.run = Timer Run [transition] a short closure allows to start timer execution.  
 t.rES = Timer rese [transition] a short closure allows to reset timer count.  
 t.rH = Timer run/hold [Status]  
 - Contact closure = timer RUN  
 - contact open = timer Hold  
 uP.du = Digital input 1 will work in parallel to the  button while digital input 2 will work in parallel to the  button.

### [10] diF2 - Digital input 2 function

**Available:** When the instrument is equipped with digital inputs.

**Range:** oFF = No function  
 AAC = Alarm Reset [status]  
 ASi = Alarm acknowledge (ACK) [status].  
 HoLd = Hold of the measured value [status].  
 r.Pic = Peaks reset [transition]  
 0.Pot = start of the 0.Pot procedure. [transition]  
 r.PoP = Start of the 0.Pot procedure and Peaks reset [transition]  
 t.rHr = Timer Run/Hold/Reset [transition]  
 t.run = Timer Run [transition] a short closure allows to start timer execution.  
 t.rES = Timer rese [transition] a short closure allows to reset timer count.  
 t.rH = Timer run/hold [Status]  
 - Contact closure = timer RUN  
 - contact open = timer Hold  
 uP.du = Digital input 1 will work in parallel to the  button while digital input 2 will work in parallel to the  buttons.

**Note:** When *diF1* is equal to *uP.du*, *diF2* setting is forced to *uP.du* and *diF2* value and cannot perform another additional function.

## Output group - Output parameters

### [11] o1F - Out 1 function

**Available:** Always.

**Range:** nonE = Output not used. With this setting the status of the this output can be driven directly from serial link  
 AL = Alarm output  
 t.out = Timer output  
 t.HoF = Timer out - OFF in Hold  
 or.bo = Out-of-range or burn out indicator  
 P.FAL = Power failure indicator  
 bo.PF = Out-of-range, burn out, Power failure indicator  
 diF.1 = The output repeats the digital input 1 status  
 diF.2 = The output repeats the digital input 2 status

**Notes:** 1. When two or more outputs are programmed in the same way, these outputs will be driven in parallel.  
 2. The power failure indicator will be reset when the instrument detect an alarm reset command by  key, digital input or serial link.

### [12] o1.AL - Alarms linked up with the out 1

**Available:** When [11] o1F = AL

**Range:** 0... 15 with the following rule:  
 +1 = Alarm 1  
 +2 = Alarm 2  
 +4 = Alarm 3  
 +8 = Alarm 4  
 + 16 = Sensor break (burn out)

**Example 1:** Setting 3 (2+1) the output will be driven by the alarm 1 and 2 (OR condition).

**Example 2:** Setting 13 (8+4+1) the output will be driven by alarm 1 + alarm 3 + alarm 4.

### [13] o1Ac - Output 1 action

**Available:** When [11] o1F is different from "nonE"

**Range:** dir = Direct action  
 rEU = Reverse action  
 dir.r = Direct action with revers LED indication  
 rEU.r = Reverse action with reverse LED indication.

**Notes:** 1. - Direct action: the output repeats the status of the driven element.

**Example:** the output is an alarm output with direct action. When the alarm is ON, the relay will be energized (logic output 1).

2. Reverse action: the output status is the opposite of the status of the driven element.

**Example:** the output is an alarm output with reverse action. When the alarm is OFF, the relay will be energized (logic output 1). This setting is usually named "fail-safe" and it is generally used in dangerous process in order to generate an alarm when the instrument power supply goes OFF or the internal watchdog starts.

### [14] o2F - Out 2 function

**Available:** When the instrument has out 2 option.

**Range:** nonE = Output not used. With this setting the status of the this output can be driven directly from serial link.

AL = Alarm output  
 t.out = Timer output  
 t.HoF = Timer out - OFF in Hold  
 or.bo = Out-of-range or burn out indicator  
 P.FAL = Power failure indicator  
 bo.PF = Out-of-range, burn out, Power failure indicator  
 diF.1 = The output repeats the digital input 1 status  
 diF.2 = The output repeats the digital input 2 status  
 St.By = Stand By status indicator

**Note:** For other details see [11] O1F parameter

### [15] o2.AL - Alarms linked up with Out 2

**Available:** When [14] o2F = AL

**Range:** 0... 15 with the following rule:  
 +1 = Alarm 1  
 +2 = Alarm 2  
 +4 = Alarm 3  
 +8 = Alarm 4  
 + 16 = Sensor break (burn out)

**Note:** For more details see [13] o1.AL parameter

### [16] o2Ac - Output 2 action

**Available:** When [14] o2F is different from “nonE”

**Range:** dir = Direct action  
rEU = Reverse action  
dir.r = Direct action with revers LED indication  
rEU.r = Reverse action with reverse LED indication.

**Note:** For more details see [13] o1.Ac parameter.

### [17] o3F - Out 3 function

**Available:** When the instrument has out 3 option

**Range:** nonE = Output not used. With this setting the status of the this output can be driven directly from serial link.  
AL = Alarm output  
t.out = Timer output  
t.HoF = Timer out - OFF in Hold  
or.bo = Out-of-range or burn out indicator  
P.FAL = Power failure indicator  
bo.PF = Out-of-range, burn out, Power failure indicator  
diF.1 = The output repeats the digital input 1 status  
diF.2 = The output repeats the digital input 2 status  
St.By = Stand By status indicator

**Note:** For other details see [11] O1F parameter

### [18] o3.AL - Alarms linked up with Out 3

**Available:** When [17] o3F = AL

**Range:** 0... 15 with the following rule:  
+1 = Alarm 1  
+2 = Alarm 2  
+4 = Alarm 3  
+8 = Alarm 4  
+ 16 = Sensor break (burn out)

**Note:** For more details see [13] o1.AL parameter

### [19] o3Ac - Output 3 action

**Available:** When [17] o3F is different from “nonE”

**Range:** dir = Direct action  
rEU = Reverse action  
dir.r = Direct action with revers LED indication  
rEU.r = Reverse action with reverse LED indication.

**Note:** For more details see [13] o1.Ac parameter.

### [20] o4F - Out 4 function

**Available:** When the instrument has out 4 option

**Range:** nonE = Output not used. With this setting the status of the this output can be driven directly from serial link.  
AL = Alarm output  
t.out = Timer output  
t.HoF = Timer out - OFF in Hold  
or.bo = Out-of-range or burn out indicator  
P.FAL = Power failure indicator  
bo.PF = Out-of-range, burn out, Power failure indicator  
diF.1 = The output repeats the digital input 1 status  
diF.2 = The output repeats the digital input 2 status  
St.By = Stand By status indicator

**Note:** For other details see [11] O1F parameter

### [21] o4.AL - Alarms linked up with Out 4

**Available:** When [20] o4F = AL

**Range:** 0... 15 with the following rule:  
+1 = Alarm 1  
+2 = Alarm 2  
+4 = Alarm 3  
+8 = Alarm 4  
+ 16 = Sensor break (burn out)

**Note:** For more details see [13] o1.AL parameter

### [22] o4Ac - Output 4 action

**Available:** When [20] o4F is different from “nonE”

**Range:** dir = Direct action  
rEU = Reverse action  
dir.r = Direct action with revers LED indication  
rEU.r = Reverse action with reverse LED indication.

**Note:** For more details see [13] o1.Ac parameter.

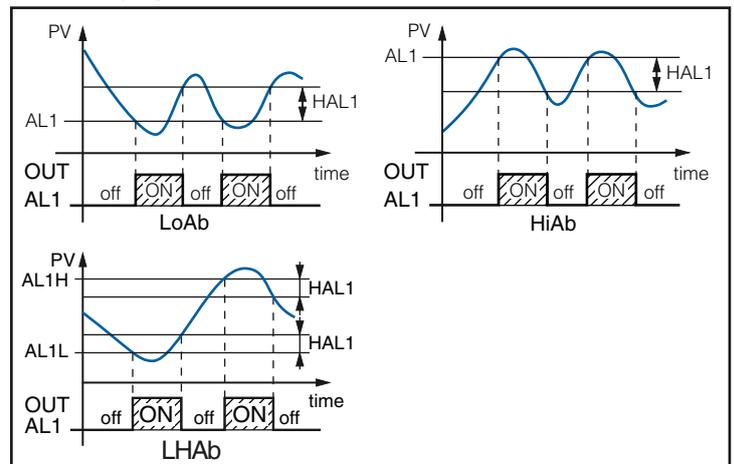
## AL1 Group - Alarm 1 parameters

### [23] AL1t - Alarm 1 type

**Available:** Always.

**Range:** nonE = Alarm not used  
LoAb = Absolute low alarm  
HiAb = Absolute high alarm  
LHAb = Absolute band alarm  
SE.br = Sensor break

**Note:** The (SE.br) sensor break alarm will be ON when the display shows ---- indication.



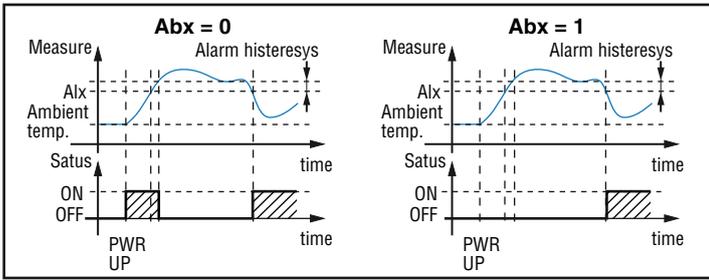
### [24] Ab1 - Alarm 1 function

**Available:** AWhen [24] AL1t is different from “nonE”

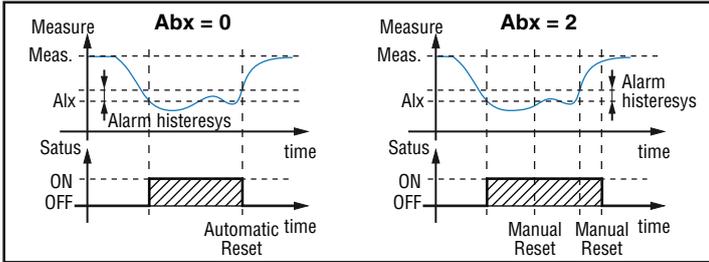
**Range:** 0... 15 with the following rule:  
+1 = Not active at power up.  
+2 = Latched alarm (manual reset)  
+4 = Acknowledgeable alarm

**Example:** setting Ab1 equal to 5 (1+4) the alarm 1 will be “not active at power up” and “Acknowledgeable”.

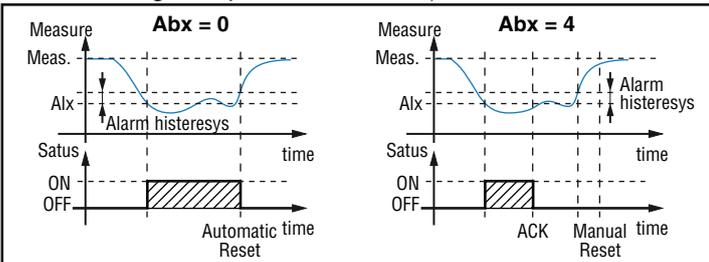
**Notes:** 1. The “not active at power up” selection allows you to inhibit the alarm function at instrument power up. The alarm will be automatically enabled when the measured value reaches, for the first time, the alarm threshold plus or minus the hysteresis (in other words, when the initial alarm condition disappears).



2. A “Latched alarm” (manual reset) is an alarm that will remain active even if the conditions that generated the alarm no longer persist. Alarm reset can be done only by an external command (U button, digital inputs or serial link).



3. An “Acknowledgeable” alarm is an alarm that can be reset even if the conditions that generated the alarm are still present. Alarm acknowledge can be done only by an external command (U button, digital inputs or serial link).



4. - The instrument does not memorize in EEPROM the alarm status. For this reason, the alarm status will be lost if a power down occurs.

**[25] AL1L - For High and low alarms, it is the low limit of the AL1 threshold**

- For band alarm, it is the low alarm threshold

**Available:** When [23] AL1t is different from “nonE” or [23] AL1t is different from “SE.br”.

**Range:** From - 1999 to [26] AL1H engineering units.

**[26] AL1H - For High and low alarms, it is the high limit of the AL1 threshold**

- For band alarm, it is the high alarm threshold

**Available:** when [23] AL1t is different from “nonE” or [23] AL1t is different from “SE.br”.

**Range:** from [25] AL1L to 9999 engineering units.

**[27] AL1- Alarm 1 threshold**

**Available:** When:

- [23] AL1t = LoAb Absolute low alarm
- [23] AL1t = HiAb Absolute high alarm
- [23] AL1t = LodE Deviation low alarm (relative)
- [23] AL1t = LidE Deviation high alarm (relative)

**Range:** From [25] AL1L to [26] AL1H engineering units.

**[28] HAL1 - Alarm 1 hysteresis**

**Available:** When [23] AL1t is different from “nonE” or [23] AL1t is different from “SE.br”.

**Range:** From 1 to 9999 engineering units

**Note:** The hysteresis value is the difference between the Alarm threshold value and the point where the Alarm automatically resets.

**[29] AL1d - Alarm 1 delay**

**Available:** When [23] AL1t different form “nonE”

**Range:** From OFF (0) to 9999 seconds

**Note:** The alarm goes ON only when the alarm condition persists for a time longer than [29] AL1d time but the reset is immediate.

**[30] AL1o - Alarm 1 enabling during out of range indications**

**Available:** when [24] AL1t different from “nonE”

**Range:** Range:

**Range:** No = Alarm NOT running when out-of-range conditions are detected.

YES = Alarm enabled when out-of-range conditions are detected.

**AL2 Group - Alarm 2 parameters**

**[31] AL2t - Alarm 2 type**

**Available:** Always

**Range:** nonE = Alarm not used

LoAb = Absolute low alarm

HiAb = Absolute high alarm

LHAb = Absolute band alarm

SE.br = Sensor break

**[32] Ab2 - Alarm 2 function**

**Available:** when [31] AL2t is different from “nonE”

**Available:** Range: 0 to 15 with the following rule:

+1 = Not active at power up.

+2 = Latched alarm (manual reset)

+4 = Acknowledgeable alarm

**Example:** setting Ad2 equal to 5 (1+4) the alarm 2 will be “not active at power up” and “Acknowledgeable”.

**Note:** For other details see [24] Ab1 parameter.

**[33] AL2L - For High and low alarms, it is the low limit of the AL2 threshold**

- For band alarm, it is is the low alarm threshold

**Available:** When [31] AL2t is different from “nonE” or [31] AL2t is different from “SE.br”.

**Range:** From - 1999 to [34] AL2H engineering units.

**[34] AL2H - For High and low alarms, it is the high limit of the AL2 threshold**

**- For band alarm, it is the high alarm threshold**

**Available:** When [31] AL2t is different from “nonE” or [31] AL2t is different from “SE.br”.

**Range:** From [33] AL2L to 9999 engineering units.

**[35] AL2 - Alarm 2 threshold**

**Available:** When:

- [31] AL2t = LoAb Absolute low alarm
- [31] AL2t = HiAb Absolute high alarm
- [31] AL2t = LodE Deviation low alarm (relative)
- [31] AL2t = LidE Deviation high alarm (relative)

**Available:** Range: from [33] AL2L to [34] AL2H engineering units.

**[36] HAL2 - Alarm 2 hysteresis**

**Available:** When [31] AL2t is different from “nonE” or [31] AL2t is different from “SE.br”.

**Range:** From 1 to 9999 engineering units

**Note:** For other details see [28] HAL1 parameter

**[37] AL2d - Alarm 2 delay**

**Available:** When [31] AL2t different form “nonE”

**Range:** From oFF (0) to 9999 seconds

**Note:** The alarm goes ON only when the alarm condition persist for a time longer than [37] AL2d time but the reset is immediate.

**[38] AL2o - Alarm 2 enabling during Stand-by mode and out of range indications**

**Available:** When [31] AL2t different from “nonE”

**Range:** No = Alarm NOT running when out-of-range conditions are detected.

YES = Alarm enabled when out-of-range conditions are detected.

**AL3 Group - Alarm 3 parameters**

**[39] AL3t - Alarm 3 type**

**Available:** Always.

**Range:** nonE = Alarm not used

LoAb = Absolute low alarm

HiAb = Absolute high alarm

LHAb = Absolute band alarm

SE.br = Sensor break

**[40] Ab3 – Alarm 3 function**

**Available:** When [39] AL3t is different from “nonE”

**Range:** 0... 15 with the following rule:

+1 = Not active at power up

+2 = Latched alarm (manual reset)

+4 = Acknowledgeable alarm

**Example:** setting Ad3 equal to 5 (1+4) the alarm 3 will be “not active at power up” and “Acknowledgeable”.

**Note:** Notes: For other details see [24] Ab1 parameter.

**[41] AL3L - For High and low alarms, it is the low limit of the AL3 threshold**

**- For band alarm, it is the low alarm threshold**

**Available:** When [39] AL3t is different from “nonE” or [39] AL3t is different from “SE.br”.

**Range:** From - 1999 to [42] AL3H engineering units.

**[42] AL3H - For High and low alarms, it is the high limit of the AL3 threshold**

**- For band alarm, it is the high alarm threshold**

**Available:** When [30] AL3t is different from “nonE” or [39] AL3t is different from “SE.br”.

**Range:** From [41] AL3L to 9999 engineering units.

**[43] AL3 - Alarm 3 threshold**

**Available:** When

- [39] AL3t = LoAb Absolute low alarm
- [39] AL3t = HiAb Absolute high alarm
- [39] AL3t = LodE Deviation low alarm (relative)
- [39] AL3t = LidE Deviation high alarm (relative)

**Range:** from [41] AL3L to [42] AL3H engineering units.

**[44] HAL3 - Alarm 3 hysteresis**

**Available:** When [39] AL3t is different to “nonE”

**Range:** From 1 to 9999 engineering units

**Note:** Notes: for other details see [28] HAL1 parameter

**[45] AL3d – Alarm 3 delay**

**Available:** When [39] AL3t different form “nonE”

**Range:** From oFF (0) to 9999 seconds

**Note:** The alarm goes ON only when the alarm condition persist for a time longer than [45] AL3d time but the reset is immediate.

**[46] AL3o - Alarm 3 enabling during Stand-by mode and out of range indications**

**Available:** when [39] AL3t different from “nonE”

**Range:** No = Alarm NOT running when out-of-range conditions are detected.

YES = Alarm enabled when out-of-range conditions are detected.

**AL4 Group - Alarm 4 parameters**

**[47] AL4t - Alarm 4 type**

**Available:** Always.

**Range:** nonE = Alarm not used

LoAb = Absolute low alarm

HiAb = Absolute high alarm

LHAb = Absolute band alarm

SE.br = Sensor break

**[48] Ab4 - Alarm 4 function**

**Available:** When [47] AL3t is different from “nonE”

**Range:** 0 to 15 with the following rule:

+1 = Not active at power up.

+2 = Latched alarm (manual reset)

+4 = Acknowledgeable alarm

**Example:** setting Ad3 equal to 5 (1+4) the alarm 3 will be “not active at power up” and “Acknowledgeable”.

**Note:** For other details see [24] Ab1 parameter.

**[49] AL4L - For High and low alarms, it is the low limit of the AL4 threshold**

- For band alarm, it is the low alarm threshold

**Available:** when [47] AL4t is different from "nonE" or [47] AL4t is different from "SE.br".

**Range:** from - 1999 to [50] AL4H engineering units.

**[50] AL4H - For High and low alarms, it is the high limit of the AL4 threshold**

- For band alarm, it is the high alarm threshold

**Available:** when [47] AL4t is different from "nonE" or [47] AL4t is different from "SE.br".

**Range:** from [49] AL4L to 9999 engineering units.

**[51] AL4 - Alarm 4 threshold**

**Available:** When:

- [47] AL4t = LoAb Absolute low alarm
- [47] AL4t = HiAb Absolute high alarm
- [47] AL4t = LodE Deviation low alarm (relative)
- [47] AL4t = LidE Deviation high alarm (relative)

**Range:** From [49] AL4L to [50] AL4H engineering units.

**[52] HAL4 - Alarm 4 hysteresis**

**Available:** When [47] AL3t is different to "nonE"

**Range:** From 1 to 9999 engineering units

**Note:** For other details see [28] HAL1 parameter

**[53] AL4d - Alarm 4 delay**

**Available:** When [47] AL4t different form "nonE"

**Range:** From oFF (0) to 9999 seconds

**Note:** The alarm goes ON only when the alarm condition persist for a time longer than [53] AL4d time but the reset is immediate.

**[54] AL4o - Alarm 4 enabling during Stand-by mode and out of range indications**

**Available:** when [47] AL4t different from "nonE"

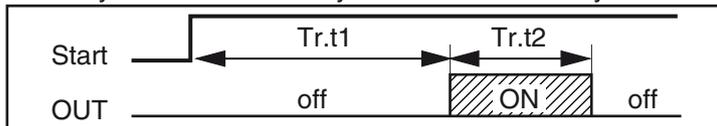
**Range:** No = Alarm NOT running when out-of-range conditions are detected.

YES = Alarm enabled when out-of-range conditions are detected.

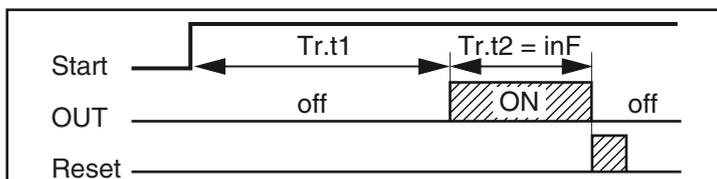
### tin Group - Timer function parameters

Five timer types are available:

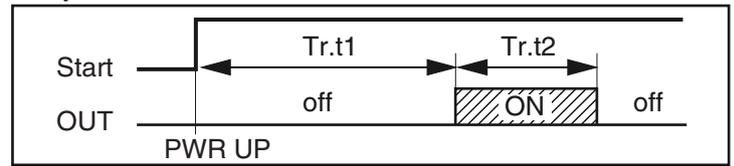
1. Delayed start with a delay time and a "end of cycle" time



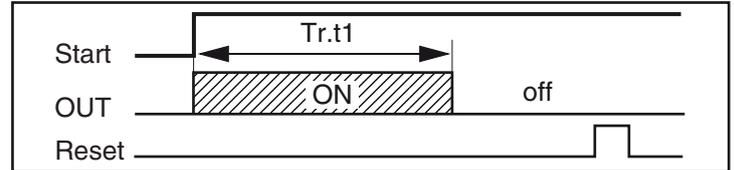
- Setting tr.t2 = Inf the timer out remains in ON condition until a reset command is detected.



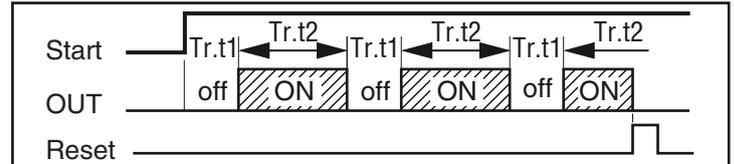
2. Delayed start at power up with a delay time and a "end of cycle" time



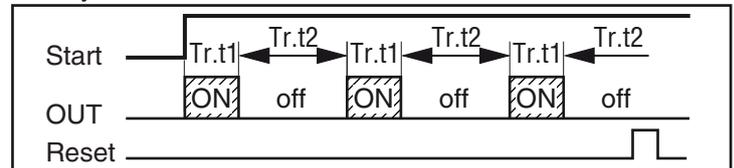
3. Feed-through



4. Asymmetrical oscillator with start in OFF



5. Asymmetrical oscillator with start in ON



**Notes:** 1. The instrument can receive the start, hold and reset commands by U button, by logic inputs and/or by serial link

2. An HOLD command can suspend the time count.

**[55] tr.F - Independent timer function**

**Available:** Always.

**Range:** nonE = Timer not used

i.d.A = Delayed start timer

i.u.P.d = Delayed start at power up

i.d.d = Feed-through timer

i.P.L = Asymmetrical oscillator with start in OFF

i.L.P = Asymmetrical oscillator with start in ON

**[56] tr.u - Engineering unit of the time**

**Available:** When [55] tr.F is different form nonE

**Range:** hh.nn = Hours and minutes

nn.SS = Minutes and seconds

SSS.d = Seconds and tenth of seconds

**Note:** Note: when the timer is running, you can see the value of this parameter but you can NOT modify it.

**[57] tr.t1 - Time 1**

**Available:** When [55] tr.F is different form nonE

**Range:** - when [56] tr.u = hh.nn from 00.01 to 99.59

- when [56] tr.u = nn.SS from 00.01 to 99.59

- when [56] tr.u = SSS.d from 000.1 to 995.9

**[58] tr.t2 - Time 2**

**Available:** When [55] tr.F is different form nonE

**Range:** - when [56] tr.u = hh.nn from 00.01 to 99.59 + inF

- when [56] tr.u = nn.SS from 00.01 to 99.59 + inF

- when [56] tr.u = SSS.d from 000.1 to 995.9 + inF

**Note:** Setting [58] tr.t2 = inF, the second time can be stopped by a reset command only.

### [59] tr.St – Timer status

**Available:** When [55] tr.F is different from nonE

**Range:** run = Timer Run  
HoLd = Timer Hold  
rES = Timer reset

**Note:** Note: this parameter allows to manage timer execution by a parameter (without digital inputs or U button).

### ↗PAN group - Operator HMI

#### [60] PAS2 - Level 2 password: Limited access level

**Available:** Always.

**Range:** oFF = Level 2 not protected by password (as level 1 = Operator level).  
1... 999.

#### [61] PAS3 - Level 3 password : configuration level

**Available:** Always.

**Range:** From 3 to 999.

**Note:** Setting [60] PAS2 equal to [61] PAS3, the level 2 will be masked.

#### [62] uSrb - U button function during RUN TIME

**Available:** Always.

**Range:** nonE = No function  
AAc = Alarm reset  
ASi = Alarm acknowledge  
HoLd = Hold of the measured value  
d.Pic = The display will show the peaks.  
r.Pic = Peaks reset  
O.Pot = Start the O.Pot routine  
r.Pot = O.Pot routine + Peaks reset  
t.Pot = Input calibration with self-learning procedure  
Str.t = Timer run/hold/reset (see note below).

**Note:** When “Timer run/hold/reset” is selected, a short press starts/stops(hold) timer count while a long press (longer than 10 second) resets the timer.

**Where:**

**nonE:** no function

**Aac:** Pushing  for 1 s at least, it is possible to acknowledge the alarm (see par. 4.3).

**ASi:** Pushing  for 1 s at least, it is possible to acknowledge an active alarm (see par. 4.3).

**HoLd:** Pushing  the measurement taken at that moment is blocked (N.B.: not the reading on the display, therefore the indication may stabilise itself with a delay that is proportional to the measuring filter). With the hold function turned on, the instrument carries out control according to the memorised measurement. Releasing the key, the instrument starts normal measurement acquisition once more.

**d.Pic:** Pressing , the maximum variation of the measurement recorded since the instrument was switched on is visualized on the display (highest/lowest peak).

**r.Pic:** Pressing , the highest and lowest peak values are re-set.

**O.Pot:** For the instruments with normalized signals input, it is possible to set the “zero” value with this function. Pressing  for at least 1 s, the display will show the writing “O.Pot” for approx. 1 s and then “0”, assuming the value measured in that instant as 0. In practice, this function allows to align the zero of the readout scaling (defined by [4] SSc and [5] FSc parameters)

with the current measured value.

An example will help us to show the result.

Input type: 0... 50 mV

[4] SSc = 0

[5] FSc = 100

[65] uSrb = O.Pot

Now, the current position is equal to 30 and I push the  button. The display will show zero and the new readout range becomes -30... +70°.

**r.POP:** For the instruments with normalized signals input, it is possible to set the “zero” value and contemporarily re-set the highest and lowest peak values with this function. Pressing  for at least 1 s, the display will show the writing “r.POP” for approx. 1 s, and then “0”, assuming the value measured in that instant as 0 and re-setting the memorized peak values.

**t.Pot:** For the instruments with normalized signals input, with this function it is possible to set the points of measurement by means of auto-ranging procedure through which the parameters “SSC”, “FSC” and “O.Pot.” are automatically re-calculated.

Pressing  for at least 1 s, the display will show “P1” alternatively to the value of the first point of setting. Now, give to the input the first point value of setting and program the value desired for that point using the  and  keys. Once the value has been set, press the  key: the instrument will memorize the value and the display will show “P2” alternatively to the value of the second point of setting. Give to the input the second point value of setting and program the value desired for that point using the  and  keys. Pressing the  key, the second value is also acquired and the instrument will automatically exit from the self-learning mode, re-calculating the measuring range.

#### [63] diSP – Display management

**Available:** Always.

**Range:** nonE = Standard display

AL1 = Alarm 1 threshold

AL2 = Alarm 2 threshold

AL3 = Alarm 3 threshold

AL4 = Alarm 4 threshold

ti.uP = When the timer is running, the display will show the timer counting up.

At the end of the counting, the instrument will show “t.End” messages alternately with the measured value.

ti.du = When the timer is running, the display will show the timer counting down.

At the end of the counting, the instrument will show “t.End” messages alternately with the measured value.

#### [64] Edit - Alarm editing enabling

**Available:** Always.

**Range:** AE = Alarm thresholds can be modified

AnE = Alarm threshold can NOT be modified

### ↗Ser group - Serial link parameter

#### [65] Add - Instrument address

**Available:** Always.

**Range:** oFF = Serial interface not used  
1... 254.

## [66] bAud - Baud rate

**Available:** When [65] Add different from oFF

**Range:** 1200 = 1200 baud  
2400 = 2400 baud  
9600 = 9600 baud  
19.2 = 19200 baud  
38.4 = 38400 baud

## COOn Group - worked time count

### [67] Co.tY – Measurement type

**Available:** Always.

**Range:** oFF = Not used  
dAY = Total worked days with threshold. It is the number of hours that the instrument is turned ON divided for 24.  
Hour = Total worked hours with threshold. It is the number of hours that the instrument is turned ON.

**Note:** It is an internal counter for machine service inspection intervals. It works every time the instrument is turned ON. When the count reaches the programmed threshold, the display shows alternately the standard display and the message “r. iSP” (requested Inspection). The count reset can be done only by changing the threshold value.

### [68] h.Job – Threshold of the working period

**Available:** When [67] Co.tY = tot.d or [67] Co.tY = tot.H

**Range:** oFF = threshold not used  
from 1 to 999 days or  
from 1 to 999 hours.

## CAL group - user calibration group

This function allows to calibrate the complete measuring chain and to compensate the errors due to:

- Sensor location;
- Sensor class (sensor errors);
- Instrument accuracy.

### [69] AL.P – Adjust Low Point

**Available:** Always.

**Range:** from -1999 to (AH.P - 10) engineering units

**Note:** The minimum difference between AL.P and AH.P is equal to 10 Engineering Units.

### [70] ALo – Adjust Low Offset

**Available:** Always.

**Range:** From -300 to 300 Engineering Units.

### [71] AH.P – Adjust High Point

**Available:** Always.

**Range:** From (AL.P + 10) to 9999 engineering units

**Note:** the minimum difference between AL.P and AH.P is equal to 10 Engineering Units.

### [72] AL.o – Adjust Low Offset

**Available:** Always.

**Range:** From -300 to 300 Engineering Units.

**Example:** Environmental chamber with an operative range from 10 to + 100 °C.

1. Insert in the chamber a reference sensor connected with

a reference instrument (usually a calibrator).

2. Start the control of the instrument, and set a set point equal to the minimum value of the operative range (e.g. 10°C).

When the temperature in the chamber is steady, take note of the temperature measured by the reference system (e.g. 9°C).

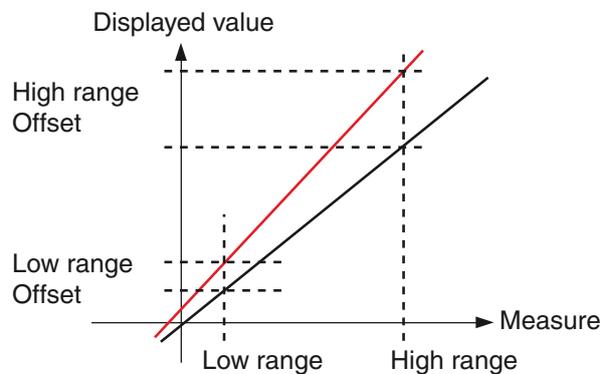
3. Set [130] AL.P = 10 (low working point) and [131] ALo = -1 (it is the difference between the reading of the instrument and the reading of the reference system).

Note that after this set the measured value of the instrument is equal to the measured value of the reference system.

4. Set a set point equal to the maximum value of the operative range (e.g. 100 °C). When the temperature in the chamber is steady, take note of the temperature measured by the reference system (e.g. 98 °C).

5. Set [132] AH.P = 100 (low working point) and [133] ALo = +2 (it is the difference between the reading of the instrument and the reading of the reference system).

Note that after this set the measured value of the instrument is equal to the measured value of the reference system.



The most important step of the configuration procedure is completed.

In order to exit from configuration parameter procedure, proceed as follows:

- Push  button.
- Push  button for more than 10 seconds.
- The instrument will come back to the “standard display”.

## 6. PARAMETERS PROMOTION

Another important step of the instrument configuration is due to the possibility to create a custom HMI (interface) in order to make the instrument easy to use for the operator and comfortable for the assistance.

By a special procedure, named promotion, the OEM can create two parameter subsets.

The first one is the “limited access” level.

This subset is protected by the password programmed by [60] PAS2 parameter.

The last subset is the “Operator” set (Level1).

This level is NOT password protected.

- Notes:**
1. The “limited access” parameter are collected in a list.
  2. The sequence of the “limited access” parameters is programmable and can be made according to your needs.
  3. The parameter sequence of the operator level is the same programmed for “limited access” level

but only specified parameters can be displayed and modified. This set must be create according to your requirements.

## 6.1 Parameters Promotion Procedure

The limited access parameter set is a list, so that, before to start promotion procedure, we suggest to operate as follows:

1. Prepare the exact parameter list you want to make accessible for limited access.
2. Number the desired parameters in the same sequence you want to have in the limited access.
3. Define which of the selected parameter will be available in Operator level also.

**Example:** I would like to obtain the following limited access list:

- AL1 - Alarm 1 threshold;
- AL3 - Alarm 2 threshold;
- HAL4 -Histeresys of the alarm 4.

But I want that the operator to be able to change AL3 threshold only. In this case the promotion will be the following:

Parameter	Promotion	Limited Access	Operator
- AL1 -	A 5	AL1	
- AL3 -	o 6	AL2	AL2
- Pb -	A 7	HAL4	

Now, proceed as follows:

1. Push the **[P]** button for more than 3 seconds.
2. The display will show alternately “PASS” and “0”.
3. By **[▲]** and **[▼]** button set a password equal to -81.
4. Push **[P]** button.

The instrument will show the acronym of the first configuration parameter group “*o 1 P*”.

5. By **[U]** button select the group of the first parameter of your list.
6. By **[P]** button select the first parameter of your list.

The instrument will show alternately the acronym of the parameter and his current promotion level.

The promotion level is defined by a letter followed by a number.

The letter can be:

c	Shows that this parameter is NOT promoted and it is present only in configuration. In this case the number is forced to zero
P	Shows that this parameter has been promoted to the limited access level. The number will show the position in the limited access list.
o	Shows that the parameter has been promoted to the Operator level. The number will show the position in the limited access list

7. By **[▲]** and **[▼]** button assign to this parameter the desired position.

**Note:** Setting a value different from 0 the letter “c” will change automatically to “P” and the parameter is automatically promoted to the limited access level.

8. In order to modify the level from limited access to operator and vice versa, push **[U]** button and, maintaining the pressure, push **[▲]** button.  
The letter will change from “P” to “o” and vice versa.

9. Select the second parameter that you want to add to the “limited access” level and repeat step 6, 7 and 8.

10.Repeat step 6, 7, 8 until the list has been completed.

- 11.When you need to exit from promotion procedure, push **[U]** button and maintain the pressure for more than 10 s.  
The instrument will show the “standard display”.

**Note:** When you set the some number to two parameter, the instrument will use only the last programmed parameter.

**Example:** In the previous example we assigned the A3 promotion level to parameter SP2. Assigning the promotion level 03 to parameter SP3 the “Limited acces” and the “Operator” list will be:

Parameter	Promotion	Limited Access	Operator
- OPEr -	o 1	OPEr	OPEr
- SP1 -	o 2	SP1	SP1
- SP3 -	o 3	SP3	SP3
- SPAt -	A 4	SPAt	
- AL1 -	o 5	AL1	AL1

## 7. OPERATIVE MODES

As we said at paragraph 4.1, when the instrument is powered, it starts immediately to work according to the memorized parameter value.

### 7.1 How to enter the “Operator Level”

The instrument is showing the “standard display”.

1. Press the **[P]** button
2. The instrument will show alternately the acronym of the first parameter promoted to this level and its value.
3. By **[▲]** and **[▼]** buttons assign to this parameter the desired value.
4. Press the **[P]** button in order to memorize the new value and go to the next parameter.
5. When you want to come back to the “standard display” push the **[U]** button for more than 5 seconds.

**Note:** The parameter modification of the Operator level is subject to a time out. If no button is pressed for more than 10 seconds, the instrument goes back to the “standard display” and the new value of the last selected parameter will be lost.

### 7.2 How to enter the “Limited Access Level”

The instrument is showing the “standard display”.

1. Press the **[P]** button for more than 5 seconds;
2. The display will show alternately “PASS” and “0”;
3. By **[▲]** and **[▼]** buttons set the value assigned to [114] PAS2 (Level 2 password).

**Notes:** 1. The factory default password for configuration parameters is equal to 20.

2. All parameter modification are protected by a time out. If no button is pressed for more than 10 second the instrument comes automatically back to the Standard display, the new value of the last selected parameter is lost and the parameter modification procedure is closed.

When you desire to remove the time out (e.g. for the first configuration of an instrument) you can use a password equal to 1000 plus the programmed password (e.g. 1000 + 20 [default] = 1020).  
It is always possible to manually End the parame-

ter configuration procedure (see below).

4. Push **[P]** button.
5. The instrument will show alternately the acronym of the first parameter promoted to this level and its value.
6. By **[▲]** and **[▼]** buttons assign to this parameter the desired value.
7. Press the **[P]** button in order to memorize the new value and go to the next parameter.
8. When you want to come back to the “standard display” push the **[U]** button for more than 5 seconds.

### 7.3 How to see but not modify the “Limited Access Parameters”

Sometime it is necessary to give to the operator the possibility to see the value assigned to the parameter promoted in the Limited Access level but it is important that all changes are made by authorized personnel only.

In this cases, proceed as follows:

1. Press the **[P]** button for more than 5 seconds
2. The display will show alternately “PASS” and “0”.
3. By **[▲]** and **[▼]** buttons set the value -181.
4. Push **[P]** button.
5. The instrument will show alternately the acronym of the first parameter promoted to the level 2 and its value.
6. Using **[P]** button it is possible to see the value assigned to all parameter present in level 2 but it will not be possible to modify it.
7. It is possible to come back to the “standard display” by pushing the **[U]** button for more than 3 seconds or by pushing no pushbutton for more than 10 seconds.

#### 7.3.1 Keyboard function when the instrument is in display mode

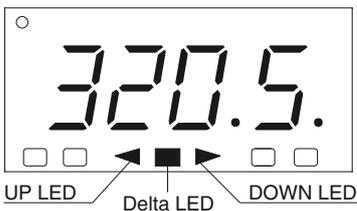
- [U]** Runs the action programmed by [116] uSrb (**[U]** button function during RUN TIME) parameter.
- [P]** Allows entry into parameter modification procedures.
- [▲]** Allows you to start the “Direct set point modification” function (see below).
- [▼]** Allows you to display the “additional informations” (see below).

#### 7.3.2 Additional informations

This instrument is able to show you some additional informations that can help you to manage your system.

The additional information is related to how the instrument is programmed, hence in many cases, only part of this information is available.

1. When the instrument is showing the “standard display” push **[▲]** button.  
The display will show the maximum measured value and turn ON the “UP” LED



2. Push **[▲]** button again. The display will show the mini-

mum measured value and turn ON the “down” LED

3. Push **[▲]** button again. The display will show the differences between the maximum and the minimum measured value and turn ON the “delta” LED.
4. Push **[▲]** button again. The display will show:
  - “h” followed by the worked hours or
  - “d” followed by the worked daysaccording to the [67] co.tY parameter setting.

## 8. ERROR MESSAGES

### 8.1 Out of Range Signals

The display shows the OVER-RANGE and UNDER-RANGE conditions with the following indications:

Over-range    Under-range  
O O O O      U.U.U.U.

The sensor break will be signalled as an out of range:

- - - -

**Note:** When an over-range or an under-range is detected, the alarms operate as in presence of the maximum or the minimum measurable value respectively.

To check the out of span Error condition, proceed as follows:

1. Check the input signal source and the connecting line.
2. Make sure that the input signal is in accordance with the instrument configuration.  
Otherwise, modify the input configuration (see section 4).
3. If no error is detected, send the instrument to your supplier to be checked.

### 8.2 List of Possible Errors

*E-EP* Possible problem of the instrument memory. The messages disappears automatically. If the error continues, send the instrument to your supplier.

## 9. GENERAL NOTES

### 9.1 Proper use

Every possible use not described in this manual must be consider as a improper use.

This instrument is in compliance with EN 61010-1 “Safety requirements for electrical equipment for measurement, control and laboratory use”; for this reason it could not be used as a safety equipment.

Whenever a failure or a malfunction of the control device may cause dangerous situations for persons, thing or animals, please remember that the plant has to be equipped with additional safety devices.

Ascon Tecnologico S.r.l. and its legal representatives do not assume any responsibility for any damage to people, things or animals deriving from violation, wrong or improper use or in any case not in compliance with the instrument’s features.

### 9.2 Warranty and Repairs

This product is under warranty against manufacturing defects or faulty materials that are found within 12 months from delivery date.

The warranty is limited to repairs or to the replacement of the

instrument.

The tampering of the instrument or an improper use of the product will bring about the immediate withdrawal of the warranty's effects.

In the event of a faulty instrument, either within the period of warranty, or further to its expiry, please contact our sales department to obtain authorisation for sending the instrument to our company.

The faulty product must be shipped to Ascon Tecnologic with a detailed description of the faults found, without any fees or charge for Ascon Tecnologic, except in the event of alternative agreements.

### **9.3 Maintenance**

This instrument does not require periodical recalibration and it has no consumable parts so that no particular maintenance is required.

Some times, a cleaning action is suggestable.

1. SWITCH THE EQUIPMENT OFF (power supply, relay out, etc.).
2. Take the instrument out of its case.
3. Using a vacuum cleaner or a compressed air jet (max. 3 kg/cm<sup>2</sup>) remove all deposits of dust and dirt which may be present on the louvers and on the internal circuits being careful not to damage the electronic components.
4. To clean external plastic or rubber parts use only a cloth moistened with:
  - Ethyl Alcohol (pure or denatured) [C<sub>2</sub>H<sub>5</sub>OH] or
  - Isopropyl Alcohol (pure or denatured) [(CH<sub>3</sub>)<sub>2</sub>CHOH] or
  - Water (H<sub>2</sub>O).
5. Make sure that there are no loose terminals.
6. Before putting the instrument back in its case, make sure that it is perfectly dry.
7. Put the instrument back and turn it ON.

### **9.4 Accessories**

The instrument has a lateral socket into which a special tool can be inserted. This tool, named A03, allows:

- To memorize a complete instrument configuration and to use it for other instruments.
- To transfer a complete instrument configuration to a PC or from a PC to an instrument
- To transfer from a PC to an instrument a complete instrument configuration
- To transfer a configuration from an A03 to another one.
- To test serial interface of the instruments and to help the OEM during machine start up.

# Appendix A

## Input Group - Main and Auxiliary Input Configuration

no.	Param.	Description	Dec. Point	Values	Default	Vis. promo
	HcFG	Parameter available by serial link shows the current hardware	0	TC/RTD TC/PTC Current Voltage	According to HW	Not displayed
	SEnS	Sensor selection (according to the hw)				A4
		nTC, Pt100 input	0	J, crAL, S, r, t, Ir.J, Ir.cA, Pt1, 0... 50 (mV), 0... 60 (mV), 12... 60 (mV)	J	
		TC, PTC, NTC input		J, crAL, S, r, t, Ir.J, Ir.cA, Ptc, ntc, 0... 50 (mV), 0... 60 (mV), 12... 60 (mV)	Ptc	
		I input		0... 20 (mA), 4... 20 (mA)	4... 20	
		V input		0... 5 (V), 1... 5 (V), 0... 10 (V), 2... 10 (V), 0... 1 (V)	0... 10	
	dP	Decimal figures	0	0... 3	0	
	SSc	Initial scale readout	dP	-1999... FSc (E.U.)	-1999	
	FSc	Final scale readout	dP	SSc... 9999 (E.U.)	9999	
	0.Pot	Offset value (to shift the zero readout)	1	SSc... FSc (E.U.)	9999	
	unit	Engineering unit	0	°C °F	0 = °C	
	FiL	Digital filter on the measured value	1	0 (oFF)... 20.0 (s)	1.0	
	diF1	Digital input 1 function	0	oFF = No function; AAC = Alarm Reset; ASi = Alarm acknowledge (ACK); HoLd = Hold of the measured value; r.Pic = Peaks reset; 0.Pot = Start of the 0.Pot procedure; r.PoP = Start of the 0.Pot procedure and Peaks reset; t.rHr = Timer Run/Hold/Reset [transition]; t.run = Timer Run [transition]; t.rES = Timer reset [transition]; t.rH = Timer run/hold [Status]; uP.du = Digital inputs in parallel to the  and  keys	OFF	A-13
	diF2	Digital input 2 function	0			A-14

## Output Group - Output Configuration

no.	Param.	Description	Dec. Point	Values	Default	Vis. promo
1	o1F	Out 1 function	0	nonE = Output not used. AL = Alarm output t.out = Timer output t.HoF = Tiemer out - OFF in Hold or.bo = Out-of-range or burn out indicator P.FAL = Power failure indicator bo.PF = Out-of-range, burn out and Power failure indicator diF.1 = The output repeats the digital input 1 status diF.2 = The output repeats the digital input 2 status	H.reg	A-16
2	o1AL	Alarms linked up with out	0	from 0 to 15 +1 = Alarm 1 +2 = Alarm 2 +4 = Alarm 3 +8 = Alarm 4 +16 = Sensor break (burn out)	AL1	A-17
3	o1Ac	Out 1 action	0	dir = Direct action rEU = Reverse action dir.r = Direct with reversed LED ReU.r = Reverse with reversed LED	dir	C-0
4	o2F	Out 2 function	0	nonE = Output not used. AL = Alarm output t.out = Timer output t.HoF = Tiemer out - OFF in Hold or.bo = Out-of-range or burn out indicator P.FAL = Power failure indicator bo.PF = Out-of-range, burn out and Power failure indicator diF.1 = The output repeats the digital input 1 status diF.2 = The output repeats the digital input 2 status	AL	A-19

no.	Param.	Description	Dec. Point	Values	Default	Vis. promo
5	o2AL	Alarms linked up with the out 2	0	from 0 to 15 + = Alarm 1 +2 = Alarm 2 +4 = Alarm 3 +8 = Alarm 4 +16 = Sensor break (burn out)	AL1	A-20
6	o2Ac	Out 2 action	0	dir = Direct action rEU = Reverse action dir.r = Direct with reversed LED ReU.r = Reverse with reversed LED	dir	C-0
7	o3F	Out 3 function	0	nonE = Output not used. AL = Alarm output t.out = Timer output t.HoF = Tiemer out - OFF in Hold or.bo = Out-of-range or burn out indicator P.FAL = Power failure indicator bo.PF = Out-of-range, burn out and Power failure indicator diF.1 = The output repeats the digital input 1 status diF.2 = The output repeats the digital input 2 status	AL	A-22
8	o3AL	Alarms linked up with the out 3	0	from 0 to 15 +1 = Alarm 1 +2 = Alarm 2 +4 = Alarm 3 +8 = Alarm 4 +16 = Sensor break (burn out)	AL2	A-23
9	o3Ac	Out 3 action	0	dir = Direct action rEU = Reverse action dir.r = Direct with reversed LED ReU.r = Reverse with reversed LED	dir	C-0
10	o4F	Out 4 function	0	nonE = Output not used. AL = Alarm output t.out = Timer output t.HoF = Tiemer out - OFF in Hold or.bo = Out-of-range or burn out indicator P.FAL = Power failure indicator bo.PF = Out-of-range, burn out and Power failure indicator diF.1 = The output repeats the digital input 1 status diF.2 = The output repeats the digital input 2 status	AL	A-24
11	o4AL	Alarms linked up with the out 4	0	from 0 to 15 +1 = Alarm 1 +2 = Alarm 2 +4 = Alarm 3 +8 = Alarm 4 +16 = Sensor break (burn out)	AL2	A-25
12	o4Ac	Out 4 action	0	dir = Direct action rEU = Reverse action dir.r = Direct with reversed LED ReU.r = Reverse with reversed LED	dir	C-0

## AL1 Group - Alarm 1 (AL1) Configuration

no.	Param.	Description	Dec. Point	Values	Default	Vis. promo
13	AL1t	Alarm 1 type	0	nonE = Alarm not used LoAb = Absolute low alarm HiAb = Absolute high alarm LHAb = Absolute band alarm SE.br = Sensor break	LoAb	A-47
14	Ab1	Alarm 1 function	0	From 0 to 15 +1 = Not active at power up +2 = Latched alarm (manual reset) +4 = Acknowledgeable alarm	0	C-0
15	AL1L	For High and low alarms, is the low limit of the AL1 threshold For band alarm, it is low alarm threshold	dP	-1999... AL1H (E.U.)	-1999	A-48
16	AL1H	For High and low alarms, is the high limit of the AL1 threshold For band alarm, it is high alarm threshold	dP	AL1L... 9999 (E.U.)	9999	A-49
17	AL1	AL1 threshold	dP	AL1L... AL1H (E.U.)	0	A-50
18	HAL1	AL1 hysteresis	dP	1... 9999 (E.U.)	1	A-51
19	AL1d	AL1 delay	dP	0 (OFF)...9999 (s)	oFF	C-0
20	AL1o	Alarm 1 enable at out of range indication	0	No = Alarm NOT running when out-of-range YES = Alarm enabled when out-of-range	no	C-0

## ▯AL2 Group - Alarm 2 (AL2) configuration

no.	Param.	Description	Dec. Point	Values	Default	Vis. promo
21	AL2t	Alarm 2 type	0	nonE = Alarm not used LoAb = Absolute low alarm HiAb = Absolute high alarm LHAb = Absolute band alarm SE.br = Sensor break	HiAb	A-54
22	Ab2	Alarm 2 function	0	From 0 to 15 +1 = Not active at power up +2 = Latched alarm (manual reset) +4 = Acknowledgeable alarm	0	C-0
23	AL2L	For High and low alarms, it is the low limit of the AL2 threshold For band alarm, it is low alarm threshold	dP	-1999... AL1H (E.U.)	-1999	A-56
24	AL2H	For High and low alarms, it is the high limit of the AL2 threshold For band alarm, it is high alarm threshold	dP	AL2L... 9999 (E.U.)	9999	A-57
25	AL2	AL2 threshold	dP	AL2L... AL2H (E.U.)	0	A-58
26	HAL2	AL2 hysteresis	dP	1... 9999 (E.U.)	1	A-59
27	AL2d	AL2 delay	dP	0 (OFF)...9999 (s)	oFF	C-0
28	AL2o	Alarm 2 enable at out of range indication	0	No = Alarm NOT running when out-of-range YES = Alarm enabled when out-of-range	no	C-0

## ▯AL3 Group - Alarm 3 (AL3) configuration

no.	Param.	Description	Dec. Point	Values	Default	Vis. promo
29	AL3t	Alarm 2 type	0	nonE = Alarm not used LoAb = Absolute low alarm HiAb = Absolute high alarm LHAb = Absolute band alarm SE.br = Sensor break	nonE	C-0
30	Ab3	Alarm 2 function	0	From 0 to 15 +1 = Not active at power up +2 = Latched alarm (manual reset) +4 = Acknowledgeable alarm	0	C-0
31	AL3L	For High and low alarms, is the low limit of the AL3 threshold For band alarm, it is low alarm threshold	dP	-1999... AL3H (E.U.)	-1999	C-0
32	AL3H	For High and low alarms, is the high limit of the AL3 threshold For band alarm, it is high alarm threshold	dP	AL3L... 9999 (E.U.)	9999	C-0
33	AL3	AL3 threshold	dP	AL3L... AL3H (E.U.)	0	C-0
34	HAL3	AL3 hysteresis	dP	1... 9999 (E.U.)	1	C-0
35	AL3d	AL3 delay	dP	0 (OFF)...9999 (s)	oFF	C-0
36	AL3o	Alarm 3 enable at out of range indication	0	No = Alarm NOT running when out-of-range YES = Alarm enabled when out-of-range	no	C-0

## ▯AL4 Group - Alarm 4 (AL4) Configuration

no.	Param.	Description	Dec. Point	Values	Default	Vis. promo
37	AL4t	Alarm 4 type	0	nonE = Alarm not used LoAb = Absolute low alarm HiAb = Absolute high alarm LHAb = Absolute band alarm SE.br = Sensor break	nonE	C-0
38	Ab4	Alarm 4 function	0	From 0 to 15 +1 = Not active at power up +2 = Latched alarm (manual reset) +4 = Acknowledgeable alarm	0	C-0
39	AL4L	For High and low alarms, it is the low limit of the AL4 threshold For band alarm, it is low alarm threshold	dP	-1999... AL4H (E.U.)	-1999	C-0
40	AL4H	For High and low alarms, it is the high limit of the AL4 threshold For band alarm, it is high alarm threshold	dP	AL4L... 9999 (E.U.)	9999	C-0
41	AL4	AL4 threshold	dP	AL4L... AL4H (E.U.)	0	C-0
42	HAL4	AL4 hysteresis	dP	1... 9999 (E.U.)	1	C-0
43	AL4d	AL4 delay	dP	0 (OFF)...9999 (s)	oFF	C-0
44	AL4o	Alarm 4 enable at out of range indication	0	No = Alarm NOT running when out-of-range YES = Alarm enabled when out-of-range	no	C-0

## TIN Group - Timer Configuration

no.	Param.	Description	Dec. Point	Values	Default	Vis. promo
45	tr.F	Independent timer function	0	NonE = Timer not used i.d.A = Delayed start timer i.uP.d = Delayed start at power up i.d.d = Feed-through timer i.PL = Asymmetrical oscillator with start in OFF i.L.P = Asymmetrical oscillator with start in ON	nonE	A-62
46	tr.u	Timer unit	0	hh.nn = Hours and minutes nn.SS = Minutes and seconds SSS.d = Second and tenth of seconds	nn.SS	A-63
47	tr.t1	Time 1	2	When tr.u = hh.nn from 00.01 to 99.59 When tr.u = nn.SS from 00.01 to 99.59 When tr.u = SSS.d from 000.1 to 995.9	1.00	A-64
48	tr.t2	Time 2	2	When tr.u = hh.nn from 00.01 to 99.59 + inF When tr.u = nn.SS from 00.01 to 99.59 + inF When tr.u = SSS.d from 000.1 to 995.9 + inF	1.00	A-65
49	tr.St	Timer status	0	HoLd = timer hold; run = timer run; rES = timer reset	rES	C-0

## PAn Group - Operator Interface Configuration

no.	Param.	Description	Dec. Point	Values	Default	Vis. promo
50	PAS2	Password level 2	0	From 0 (oFF) to 999 (oFF = Level 2 not protected by psw)	20	A-93
51	PAS3	Password level 3	0	From 3 to 999	30	C-0
52	uSrb	<input type="checkbox"/> button function during run time	0	nonE = No function AAc = Alarm reset ASi = Alarm acknowledge HoLd = Hold of the measured value d.Pic = The display will shows the peaks r.Pic = Peaks reset 0.Pot = Start the 0.Pot routine r.Pot = 0.Pot routine + Peaks reset t.Pot = Input calibration with self-learning procedure Str.t = Timer run/hold/reset	nonE	A-94
53	diSP	Display management	0	nonE = Standard display AL1 = Alarm 1 threshold AL2 = Alarm 2 threshold AL3 = Alarm 3 threshold ti.uP = Timer time up ti.du = Timer time down	nonE	A-95
54	Edit	Alarm editing enable	0	AE = Alarm thresholds can be modified AnE = Alarm threshold can NOT be modified	ANe	

## Ser Group - Serial Communications Interface Configuration

no.	Param.	Description	Dec. Point	Values	Default	Vis. promo
55	Add	Address	0	0 (oFF)... 254	1	C-0
56	bAud	Baud rate	0	1200 (bit/s); 2400 (bit/s); 9600 (bit/s); 9.2 (kbit/s); 38.4 (kbit/s)	9600	C-0

## COOn Group - Consumption Parameters Configuration

no.	Param.	Description	Dec. Point	Values	Default	Vis. promo
57	co.ty	Measurement type	0	oFF = Not used dAY = Total worked days Hour = Total worked hours	nonE	A-97
58	h.Job	Threshold of the worked hours/days	0	From 0 (oFF) to 9999 (days/hours)	oFF	A-100

## ▯CAL Group - User Calibration Parameters Configuration

no.	Param.	Description	Dec. Point	Values	Default	Vis. promo
59	A.L.P	Adjust low Point	dP	From -1999 to AH.P-10 (E.U.)	0	A-9
60	A.L.o	Adjust low Offset	dP	From -300 to 300 (E.U.)	0	A-10
61	A.H.P	Adjust High Point	dP	From A.L.P +10 to 9999 (E.U.)	9999	A-11
62	A.H.o	Adjust High Offset	dP	From -300 to 300 (E.U.)	0	A-12

